

LECTURE 16

HYPERBOLIC GEOMETRYTwo models for \mathbb{H}^3 :

$$\underline{\text{UHS}} = \{(z, t) \in \mathbb{C} \times \mathbb{R} \mid t > 0\}$$

$$\underline{\text{BM}} = \{x \in \mathbb{R}^3 \mid |x| < 1\}$$

$$ds_{\text{UHS}} = \frac{ds_{\mathbb{E}}}{t} \quad \text{and} \quad ds_{\text{BM}} = \frac{2ds_{\mathbb{E}}}{1-r^2}, \quad r^2 = x_1^2 + x_2^2 + x_3^2$$

Fix $\gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{SL}(2, \mathbb{C})$.Set $q = z + tj$ in the quaternions (i.e. $q = x + iy + tj$).

Define. $\gamma(q) = (aq + b)(cq + d)^{-1} = (cq + d)^{-1}(aq + b)$

Q. Check this equality (the quaternions are not commutative) and show that $\gamma(q) \in \text{UHS}$, i.e. k -coord. is zero, j -coord. > 0 .

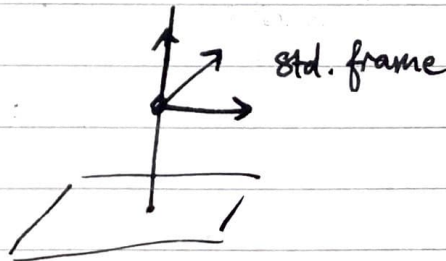
Q. γ acts via isometry on UHS. [Ahlfors]

Q. The action factors through $\text{PSL}(2, \mathbb{C})$.

Q. The stabiliser of $(0, 0, 1)$ in $\text{SL}(2, \mathbb{C})$ is $\text{SU}(2)$.
Thus, $\text{PSL}(2, \mathbb{C})$ acts simply transitively on right-handed orthonormal frames to UHS.

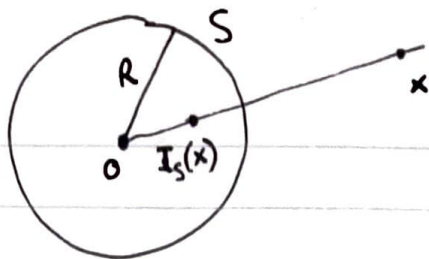
$$\underline{\text{Thus}}, \quad \text{SL}(2, \mathbb{C}) \cong \text{SU}(2) \times \mathbb{H}^3$$

(Simply transitively means that γ determines and is determined by its action on the std. frame.)



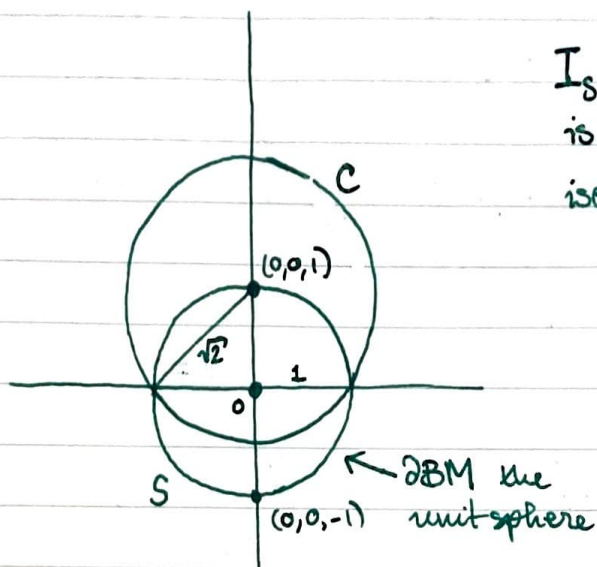
$$\underline{\text{Thus}}, \quad \text{PSL}(2, \mathbb{C}) \cong \text{Isom}^+(\mathbb{H}^3)$$

Q. Every $\gamma \in \text{Isom}^+(\mathbb{H}^3)$ is a product of two inversions in spheres.



Inversion in the sphere S :
 $I_S: \widehat{\mathbb{R}^3} \rightarrow \widehat{\mathbb{R}^3}$
 preserves rays, and
 $|I_S(x)||x| = R^2$.

2.



$I_S \circ I_C: \text{UHS} \rightarrow \text{BM}$
 is an (orientation-preserving)
 isometry.

So can conjugate action of $\text{PSL}(2, \mathbb{C})$ by $I_S \circ I_C$ and realize $\text{Isom}^+(\text{BM})$ as a subgroup of (orientation-preserving) Möbius transformations (where a Möbius transf. is any product of inversions in spheres).

Rk. Note that UHS, BM are conformal models, i.e. angles in the model and in \mathbb{E}^3 agree.

Pf. $\left[ds_{\text{UHS}} = \frac{ds_{\mathbb{E}}}{v} \right]$

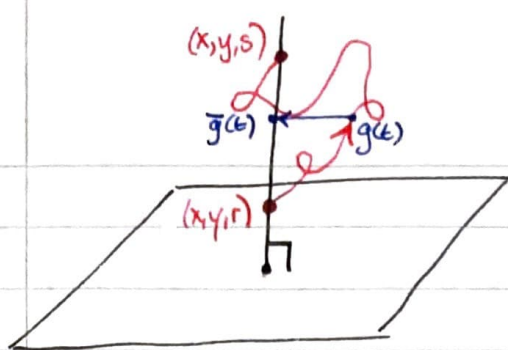
Not conformal: Klein model, hyperboloid model, exponential model.

GEODESICS (following P. Scott's BLMS article)

[BTW. Skipped: types of isometry (identity, elliptic, parabolic, hyperbolic, loxodromic).

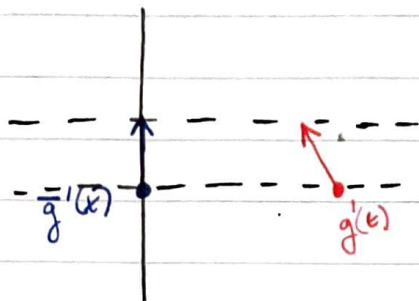
2. Vertical arcs in UHS are geodesics.

Pf. $\left[\text{Suppose } g: [0,1] \rightarrow \text{UHS} \text{ has } g(0) = (x,y,r), g(1) = (x,y,s) \right]$



Let $g(t) = (g_1(t), g_2(t), g_3(t))$.

Define $\bar{g}(t) = (x, y, g_3(t))$.



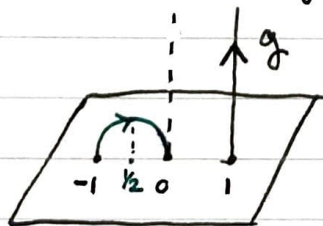
Claim: $|g'(t)| \geq |\bar{g}'(t)|$, with inequality if g is not vertical.

$\Rightarrow \text{length}(g) \geq \text{length}(\bar{g})$.

Q.

If g_3' changes sign, then \bar{g} is not a geodesic. (We could chop out bits of the path and get a shorter path)

Z. The element $g = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ sends $g(t) = 1 + tj$ to a hemi-circle from -1 to 0 .



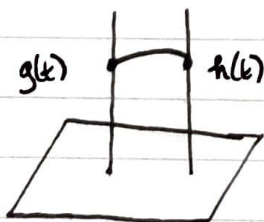
Cor. Arcs of hemispheres are geodesics.

Q.

In fact, $d_{\mathbb{H}^3}((0,0,r), (0,0,s)) = \log\left(\frac{s}{r}\right)$ (if $s > r$).

Q.

Suppose g, h are vertical geodesics, parametrized with unit speed. Show that the distance $d_{\mathbb{H}^3}(g(t), h(t)) = \text{const.} + \text{exp. decay}$.



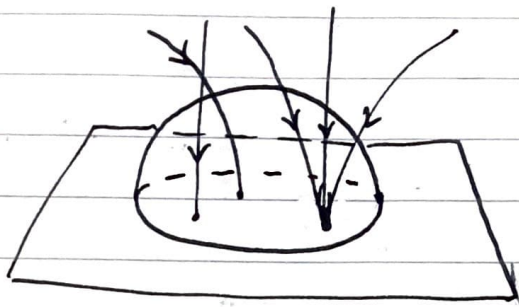
Defn. Call two such geodesics **asymptotic**.

This is an equivalence relation, on oriented geodesics.

Take quotient to get $\partial_{\infty} \mathbb{H}^3$.

get a topology from hemispheres.

If H is a hemisphere (transversely-oriented) perpendicular to \mathbb{C} , then all geodesics crossing H in same direction is an open set.



Q.

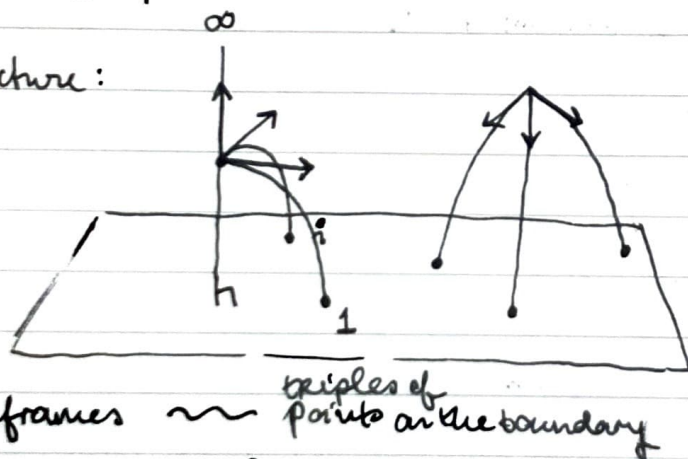
$$\partial_{\infty} \mathbb{H}^3 \cong \mathbb{S}^2.$$

Key fact: the action of $\mathrm{PSL}(2, \mathbb{C}) \cong \mathrm{Isom}(\mathbb{H}^3)$ on $\partial_{\infty} \mathbb{H}^3$ is simply three-transitive.

[γ determines and is determined by its action on any three distinct points of $\partial_{\infty} \mathbb{H}^3 \cong \mathbb{C} \cup \{\infty\}$.]

[Hint for proof: use KAN decomposition of $\gamma \in \mathrm{PSL}(2, \mathbb{C})$.]

[Picture:



frames \rightsquigarrow triples of points on the boundary

By applying a ^①parabolic matrix, we can move the base pt. to the ~~base pt. of the std~~ line above 0,

by applying a ^②hyperbolic matrix, we can slide the base pt. along the line to the base pt. of the std. frame,

by applying an ^③elliptic matrix, we can rotate the frame to the std. frame!]

Claim. The frame bundle over \mathbb{H}^3 is isomorphic to $(\mathbb{S}^2)^3 \setminus \Delta$,
i.e. $(\partial_{\infty} \mathbb{H}^3)^3 \setminus \Delta$.