

## CAT(0) metric spaces.

Many of the most interesting groups are not hyperbolic

Sometimes this can be easily seen because they contain a copy of  $\mathbb{Z}^2$  - eg

- $SL(n, \mathbb{Z})$  for  $n \geq 3$ , and other lattices in semi-simple Lie groups
- Mapping class groups of compact surfaces of genus  $\geq 2$ .
- Automorphism groups of free groups

Sometimes there are more subtle reasons, eg

- Baumslag-Solitar groups  
 $BS(1, n) = \langle a, b \mid bab^{-1} = a^n \rangle, n \geq 2$

We would still like to study them using the Svarc-Milnor lemma and curvature constraints.

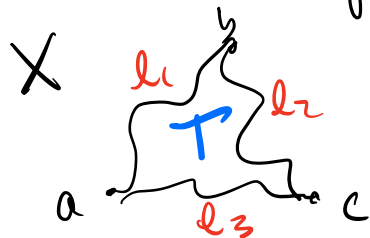
A notion of curvature for a general metric space was studied by Gromov, based on work by Caratheodory, Alexandrov and Toponogov,

so he called it  $CAT(K)$ , where  $K \in \mathbb{R}$  is the "curvature".

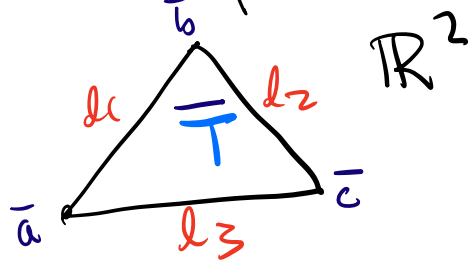
In particular,  $CAT(0)$  is a notion of non-positive curvature

It is also defined in terms of triangles, but is "less fuzzy" than the notion of  $\delta$ -thin triangles used in the definition of hyperbolicity.

Let  $X$  be a geodesic metric space



$T$  = geodesic triangle  
 $l_1, l_2, l_3$  satisfy triangle inequality



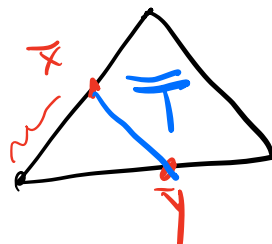
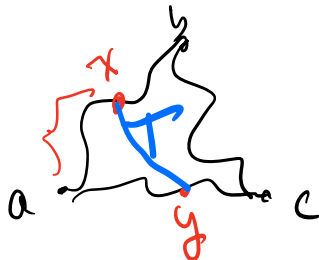
$\bar{T}$  = triangle in  $\mathbb{R}^2$  with same side lengths.  
 "comparison triangle"

Def  $X$  = proper geodesic metric space

is **CAT(0)** if every geodesic triangle

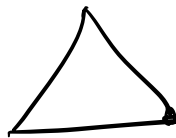
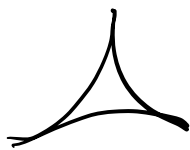
$T$  is thinner than  $\bar{T}$ , i.e.

for  $x, y \in T$ , let  $\bar{x}, \bar{y}$  be the corresponding points in  $\bar{T}$ :

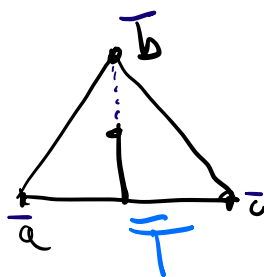
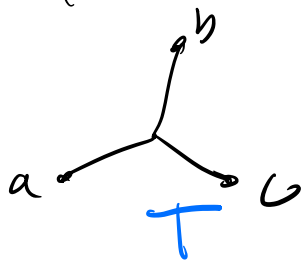


then  $d_X(x, y) \leq d_{\mathbb{R}^2}(\bar{x}, \bar{y})$

Example:  $\mathbb{H}^2$  is CAT(0)



Example: A tree is CAT(0)



$\mathbb{R}^2$

Example:  $\mathbb{R}^n$  is CAT(0)

Exercise: If  $X, Y$  are CAT(0) then  $X \times Y$  is, where

$$d((x_1, y_1), (x_2, y_2)) = \sqrt{d_X(x_1, x_2)^2 + d_Y(y_1, y_2)^2}$$

In particular, products  $T_1 \times T_2$  of trees are CAT(0)

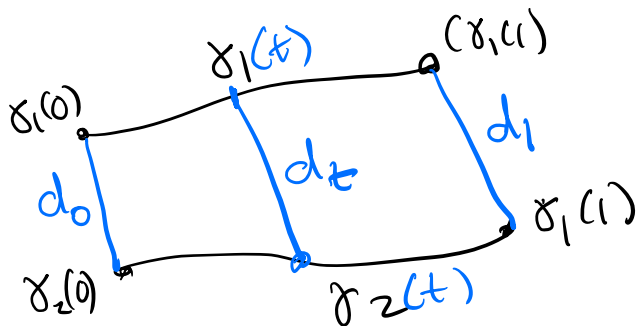
Theorem  $X \text{ CAT}(0) \Rightarrow$  there is a unique geodesic between any two points.

Lemma:  $X \text{ CAT}(0)$ ,  $\gamma_1, \gamma_2: [0,1] \rightarrow X$  geodesics then

$$d(\gamma_1(t), \gamma_2(t)) \leq (1-t)d(\gamma_1(0), \gamma_2(0)) + td(\gamma_1(1), \gamma_2(1))$$

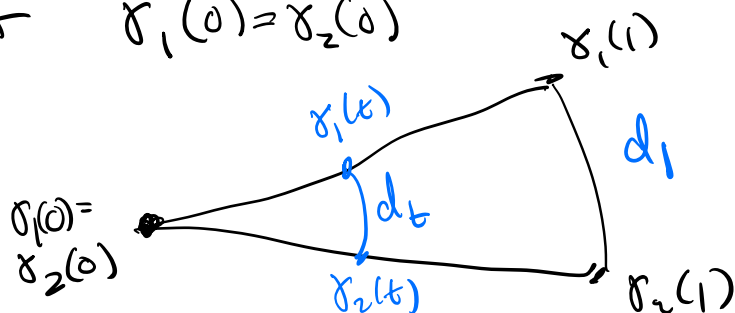
Proof:

Picture:

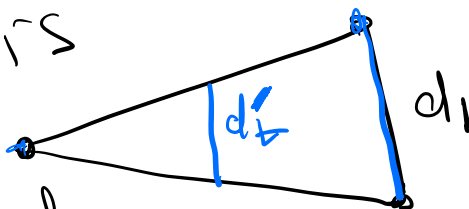


We want:  $d_t \leq (1-t)d_0 + t \cdot d_1$

If  $\gamma_1(0) = \gamma_2(0)$

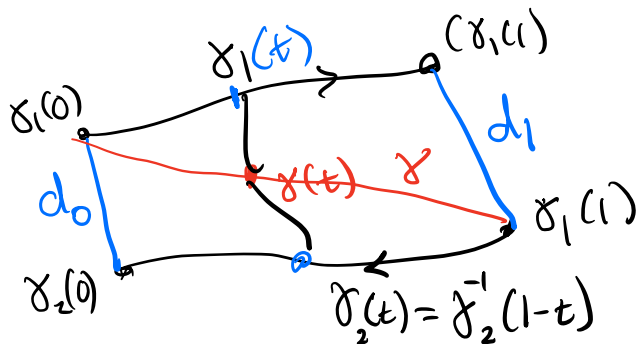


The comparison triangle is



$$\text{So } d_t \leq d'_t = t \cdot d_1$$

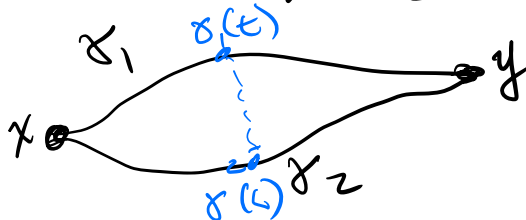
In general



$$\begin{aligned} d_t = d(x_1(t), x_2(t)) &\leq d(x_1(t), \gamma(t)) + d(\gamma(t), x_2(t)) \\ &\leq t d_1 + (1-t) d_0 \quad \checkmark \end{aligned}$$

The theorem is now a corollary:

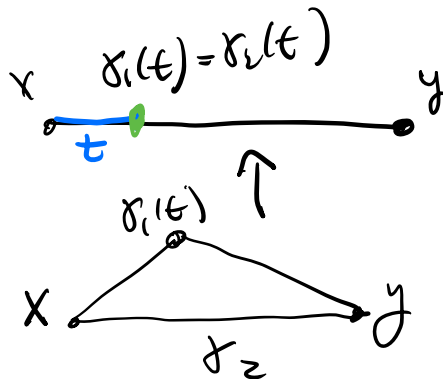
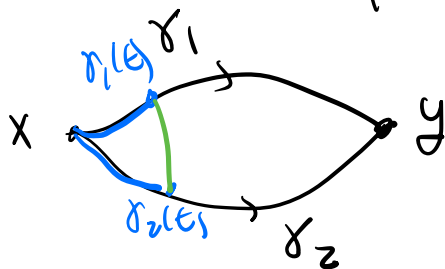
Let  $\gamma_1, \gamma_2$  be two geodesics from  $x$  to  $y$ . Then  $\gamma_1 = \gamma_2$ .



pf

$$\begin{aligned} d(\gamma_1(t), \gamma_2(t)) &\leq t d_1 + (1-t) d_0 \\ &= t \cdot 0 + (1-t) \cdot 0 = 0 \quad \checkmark \end{aligned}$$

Note: Easier proof:



Look at comparison  $\Delta$  for  $X$   
 Get  $d(\gamma_1(t), \gamma_2(t)) \leq 0$   
 $\Rightarrow \gamma_1(t) = \gamma_2(t)$ .

We can use this to prove the following:

Theorem: A CAT(0) metric space  $X$  is contractible

We need

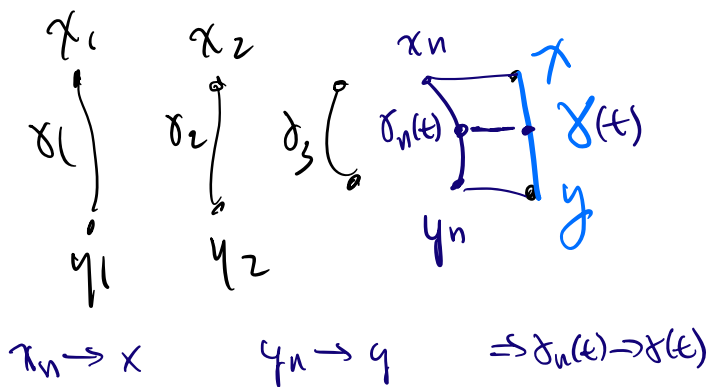
Lemma: Geodesics vary continuously with their endpoints.

ie  $x_n \rightarrow x$        $y_n \rightarrow y$   
 let  $\gamma_n: [0,1] \rightarrow X$  be the geodesic  $x_n$  to  $y_n$   
 $\gamma: [0,1] \rightarrow X$  the geodesic  $x$  to  $y$

Then  $\{\gamma_n\} \rightarrow \gamma$

Proof Convergence here means in the compact-open topology.

The previous lemma guarantees pointwise convergence



Then compactness of  $[0,1]$  allows us to apply the Arzela-Ascoli theorem to get uniform convergence.

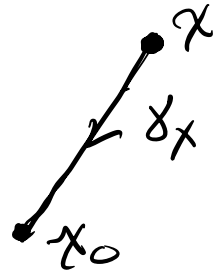


## Proof of theorem (contractibility) :

Fix  $x_0 \in X$

For any  $x \in X$ ,

let  $\gamma_x$  be the unique  
geodesic  $x$  to  $x_0$



Define  $F: X \times [0, 1] \rightarrow X$   
 $(x, t) \mapsto \gamma_x(t)$

This is a continuous map.

$$F(0) = \text{id}$$

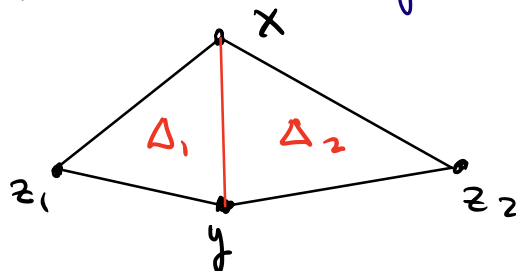
$$F(1) \equiv x_0$$

ie  $F$  is a homotopy from  $X$  to  $\{x_0\}$

We can get new CAT(0) spaces from  
old ones by a gluing procedure,

based on the following Lemma

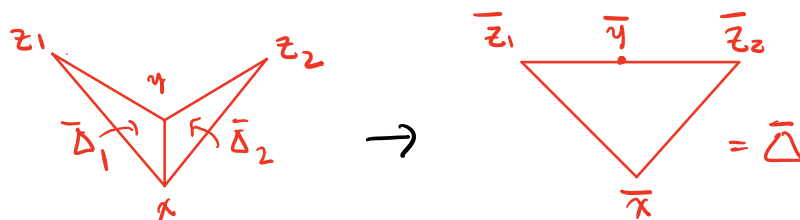
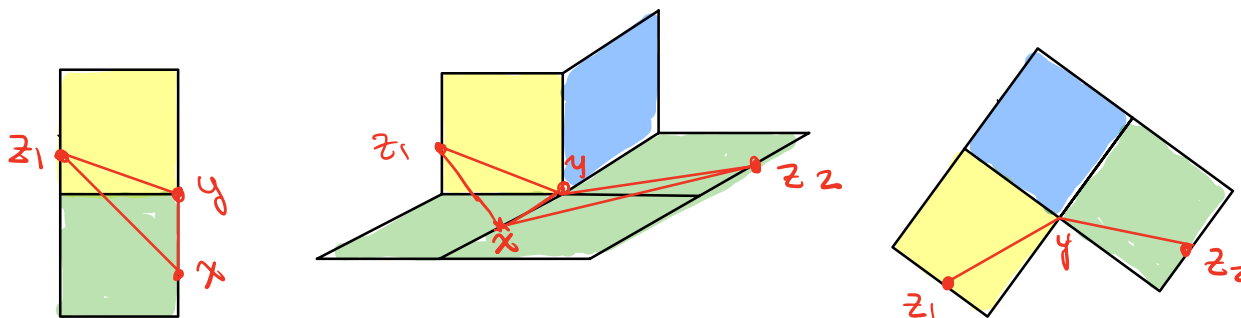
Alexandrov Lemma Let  $\Delta(x, z_1, z_2)$  be a geodesic triangle with vertices  $x, z_1, z_2$  and  $y$  a point on the geodesic  $[z_1, z_2]$



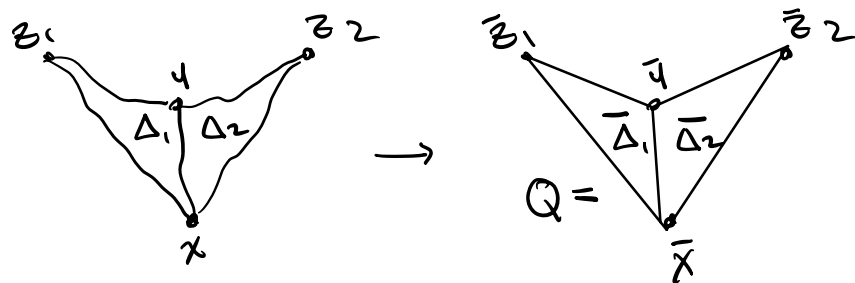
$$\Delta_1 = \Delta(x, y, z_1), \quad \Delta_2 = \Delta(x, y, z_2)$$

If  $\Delta_1$  and  $\Delta_2$  satisfy the CAT(0) condition, then so does  $\Delta(x, z_1, z_2)$ .

Example to keep in mind: hallway corner

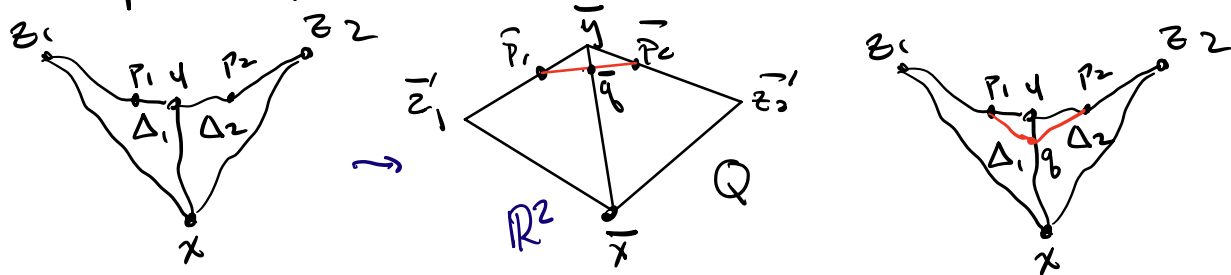


Proof: Look at the quadrilateral  $Q$  formed by  $\bar{\Delta}_1$  and  $\bar{\Delta}_2$  in  $\mathbb{R}^2$ :



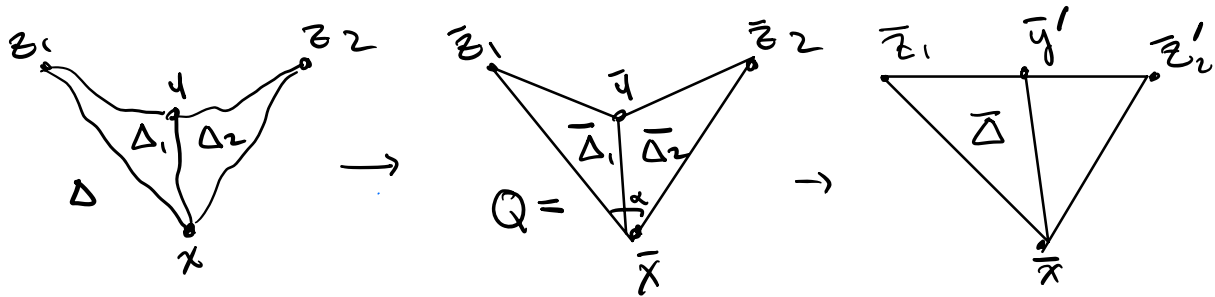
Claim  $\angle(\bar{z}_1, \bar{y}, \bar{x}) + \angle(\bar{z}_2, \bar{y}, \bar{x}) \geq \pi$

Proof: Suppose it is  $< \pi$ . Choose  $p_1 \in [z_1, y]$  and  $p_2 \in [z_2, y]$ .



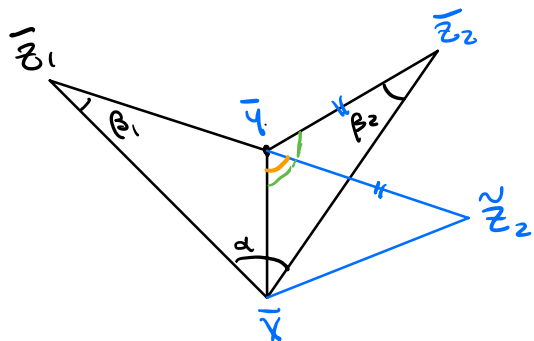
$$\begin{aligned}
 \text{Then } d_x(p_1, p_2) &= d_x(p_1, y) + d_x(y, p_2) \\
 &= d_{\mathbb{R}^2}(\bar{p}_1, \bar{y}) + d_{\mathbb{R}^2}(\bar{y}, \bar{p}_2) \\
 &> d_{\mathbb{R}^2}(\bar{p}_1, \bar{q}) + d_{\mathbb{R}^2}(\bar{q}, \bar{p}_2) \\
 &\geq d_x(p_1, q) + d_x(q, p_2) \\
 &\geq d_x(p_1, p_2) \quad *
 \end{aligned}$$

Now we straighten  $Q$  to obtain the comparison triangle  $\bar{\Delta}$  for  $\Delta$ :



Claim: straightening increases the angles at  $\bar{z}_1, \bar{z}_2$  and  $\bar{x}$

Proof: continue the edge  $\bar{z}_1\bar{y}$  and mark  $\tilde{z}_2$  on it with  $d(\bar{y}, \tilde{z}_2) = d(y, \bar{z}_2)$ :

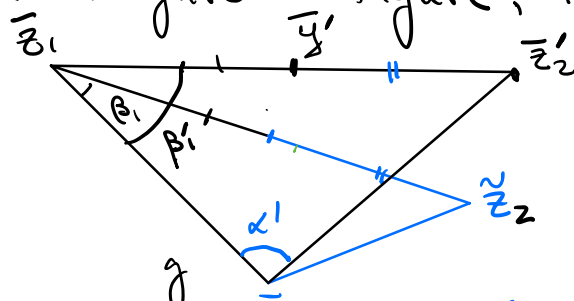


$$\angle \bar{x}\bar{y}\tilde{z}_2 \leq \angle \bar{x}\bar{y}\bar{z}_2$$

$$\Rightarrow d(\bar{x}, \tilde{z}_2) \leq d(\bar{x}, \bar{z}_2)$$

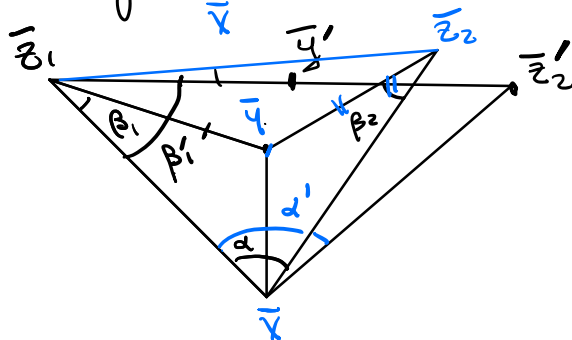
(law of cosines)

in the straightened figure, this implies  $\beta'_1 \geq \beta_1$



(law of cosines again)

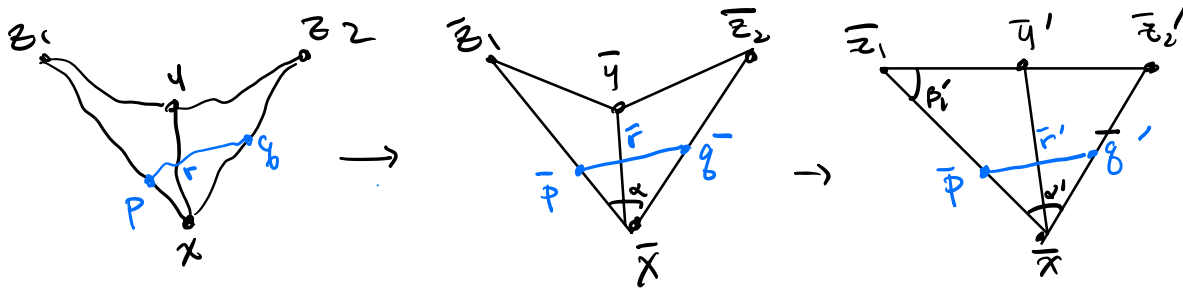
and



$$d(\bar{z}_1, \bar{z}_2) \leq d(\bar{z}_1, \bar{y}) + d(y, \bar{z}_2) = d(\bar{z}_1, \bar{z}'_2) \Rightarrow \alpha < \alpha'$$

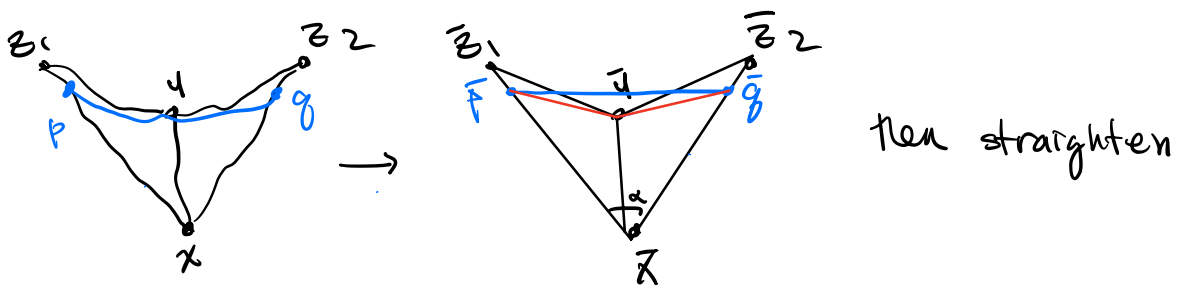
Now for the CAT(0) inequality:

If  $[\bar{p}, \bar{q}]$  stays in  $Q$ , this is clear: eg:

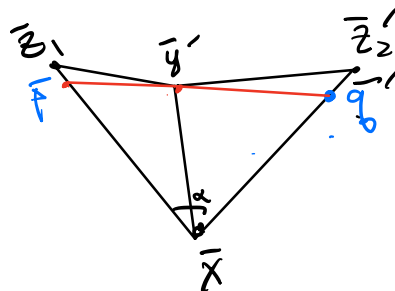


$$\begin{aligned}
 d(p, q) &= d(p, r) + d(r, q) \leq d(\bar{p}, \bar{r}) + d(\bar{r}, \bar{q}) \\
 &\quad (\text{because } \Delta_1, \Delta_2 \text{ are CAT}(0)) \\
 &= d(\bar{p}, \bar{q}) \\
 &\leq d(\bar{p}, \bar{q}') \text{ since } \alpha' \geq \alpha
 \end{aligned}$$

If  $[\bar{p}, \bar{q}]$  leaves  $Q$ :

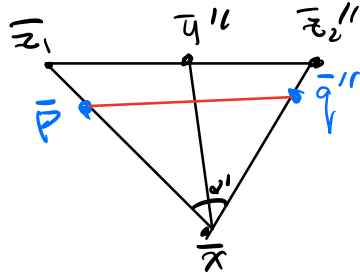


until it passes through  $\bar{y}'$



The red distances are larger since  $\beta_1$  and  $\beta_2$  are larger.

Continue to straighten; then  $d(\bar{p}, \bar{q}')$  grows  
 since  $\alpha$  grows, as before.



So, in the end

$$\begin{aligned}
 d(p, q) &= d(p, y) + d(y, q) \\
 &\leq d(\bar{p}, \bar{y}) + d(\bar{y}, \bar{q}) \\
 &\text{(because } \Delta_1, \Delta_2 \text{ are CAT}(0)) \\
 &\leq d(\bar{p}, \bar{q}') \\
 &\leq d(\bar{p}, \bar{q}'') \quad \checkmark
 \end{aligned}$$

Easy corollary:

$X_1, X_2 \text{ CAT}(0)$ ,  $Y_1 \subset X_1$ ,  $Y_2 \subset X_2$

$Y_i$  convex, both  $\cong Y$ .

Then  $X_1 \cup_Y X_2$  is  $\text{CAT}(0)$

Pf.: **Exercise**

eg  $X_1, X_2 \text{ CAT}(0)$   $X_1 \vee X_2$

  $X_1 \vee X_2$  is  $\text{CAT}(0)$

## CAT(0) groups

Definition A group  $G$  is CAT(0) if it acts properly and cocompactly on a CAT(0) space  $X$ .

Recall that CAT(0) metric spaces are assumed to be proper, so we may apply Svarc-Milnor to conclude that  $G$  is quasi-isometric to  $X$ .

Unlike hyperbolicity, the CAT(0) property is not a quasi-isometry invariant, so there is no obvious space to use to determine whether  $G$  is CAT(0).

(It is an open problem whether every hyperbolic group is also CAT(0).)

If  $G_1$  and  $G_2$  are CAT(0),  
 $G_1 \curvearrowright X_1$ ,  $G_2 \curvearrowright X_2$  cocompact, proper  
 $\Rightarrow G_1 \times G_2 \curvearrowright X_1 \times X_2$  is cocompact and proper

By your exercise,

$X_1, X_2$  CAT(0)  $\Rightarrow X_1 \times X_2$  CAT(0), so

$G_1 \times G_2$  is also CAT(0)



We can use Alexandrov's lemma to prove that free products  $G_1 * G_2$  are CAT(0) as follows.

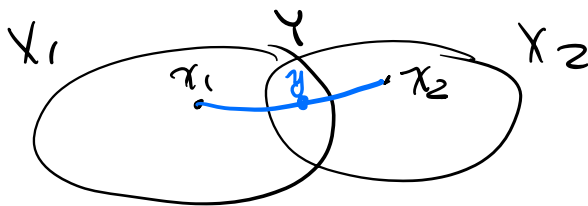
First note Alexandrov can be used to prove:

Prop Let  $X_1, X_2$  be CAT(0) spaces with isometric convex subspaces  $Y_1 \subset X_1, Y_2 \subset X_2$   
 $(Y_1 \cong Y_2 \cong Y)$

Then  $X_1 \cup_Y X_2$  is CAT(0)

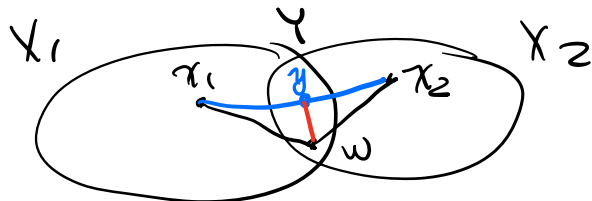
Proof Let  $\Delta(x_1, x_2, w)$  be a geodesic triangle in  $X_1 \cup_Y X_2$

If  $\Delta \subset X_1$  or  $\Delta \subset X_2$  it is CAT(0), so assume  $x_1 \in X_1 - Y, x_2 \in X_2 - Y$

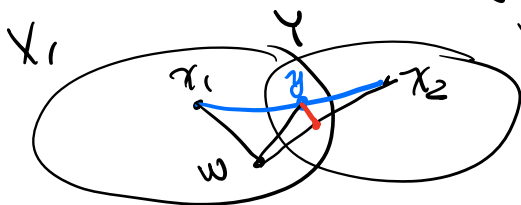


The geodesic  $[x_1, x_2]$  must pass through  $Y$ , so contains some  $y \in Y$

If  $w \in Y$ , then by convexity  $[w, y] \subset Y$ ,  
 so Alexandrov  $\Rightarrow \Delta(w, x_1, x_2)$  is CAT(0)



If  $w \in X_1$ , then  $\Delta(w, y, x_2)$  is CAT(0) by



the same argument,  
 so again  
 Alexandrov  $\Rightarrow$   
 $\Delta(x_1, w, x_2)$  is  
 CAT(0)

(similar if  $w \in X_2$ )  $\checkmark$

A space is **locally CAT(0)** (also called **NPC** - for "non-positively curved") if every point has a CAT(0) neighborhood

Theorem If  $Y$  is NPC, its universal cover  $\tilde{Y}$  is a complete CAT(0) space.

The proof occupies a chapter in B-H (Chapter II.4 - The Cartan-Hadamard theorem) - we will not prove it.

So if  $Y$  is NPC and compact,  
 $\pi_1(Y)$  is CAT(0).

Now suppose  $G_1$  and  $G_2$  are torsion-free. CAT(0)  
Then  $G_1 \curvearrowright X_1$  and  $G_2 \curvearrowright X_2$  are free and proper, so  $X_1 \rightarrow X_1/G_1$  and  $X_2 \rightarrow X_2/G_2$  are covering spaces.

Since  $X_1, X_2$  are contractible they are the universal covers of  $Y_i = X_i/G_i$   
so  $\pi_1(Y_i) = G_i$

Further more,  $Y_1 \vee_y Y_2$  is locally CAT(0);  
the only point to check is  $y$ .

If  $U_1$  is a CAT(0) nbd of  $y$  in  $Y_1$  and  $U_2$  is a CAT(0) nbd in  $Y_2$ , then  $U_1 \cap U_2 = \{y\}$

and  $U_1 \cup U_2$  is CAT(0) by the Proposition.

$\therefore G_1 * G_2 = \pi_1(Y_1, V_y, Y_2)$  acts on  $\widehat{(Y_1, V_y, Y_2)}$ , which  
is CAT(0) by the Cartan-Hadamard  
theorem, so  $G_1 * G_2$  is CAT(0)

## Properties of CAT(0) groups.

CAT(0) groups share a number of "tameness" properties with hyperbolic groups, but to prove them usually requires different methods.

For example

Theorem A CAT(0) group  $G$  has only finitely many conjugacy classes of finite subgroups.

This is also true for hyperbolic groups. You proved this in the exercises for finite cyclic subgroups of hyperbolic groups, using the fact that long loops have uniformly short segments that are not geodesics. But that's not true for CAT(0) spaces.

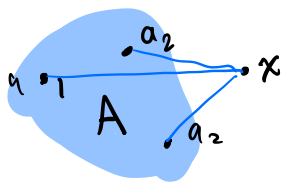
We will use a different idea:

First show any finite subgroup  $H$  of  $G$  fixes a point of the CAT(0) space  $X$ .

Then use properness of the action to reach the conclusion.

The fixed point will be the "center" of an orbit  $H \cdot x_0$ , which is a finite set. When you act by  $h \in H$ , the orbit  $Hx_0$  doesn't move, so its center doesn't move.

Let  $A$  be a finite set. To find a center:



For any  $x \in X$ , define

$$r(x, A) = \max_{a \in A} d(x, a) \quad (\text{so } A \subset \overline{B}_r(x))$$

$$\text{And } r(A) = \inf_{x \in X} r(x, A)$$

If  $r(x, A) = r(A)$ ,  $x$  is called a circumcenter for  $A$ .

Proposition Every finite set  $A$  has a unique circumcenter.

To prove this, we will prove an inequality relating  $r(x, A)$ ,  $r(y, A)$ ,  $d(x, y)$  and  $r(A)$ :

$$d(x, y)^2 \leq 2(r(x, A)^2 + r(y, A)^2 - 2r(A)^2)$$

This immediately gives uniqueness:

If  $r(x, A) = r(A)$  and  $r(y, A) = r(A)$   
then  $d(x, y) = 0$

To get existence, take a sequence  $\{x_n\}$   
of points in  $X$  such that  
 $r(x_n, A) \rightarrow r(A)$

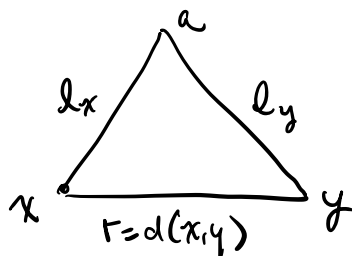
Then  $d(x_i, x_j)^2 \leq 2(r(x_i, A)^2 + r(x_j, A)^2 - 2r(A)^2)$   
 $\rightarrow 0$  as  $i, j \rightarrow \infty$

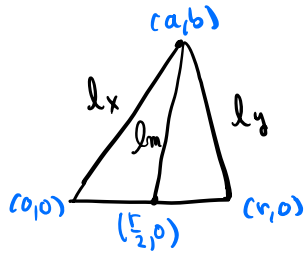
So  $\{x_n\}$  is a Cauchy sequence  
The Cartan-Hadamard theorem implies that a  
CAT(0) space with a proper cocompact  
group action must be complete,

so  $\{x_n\} \rightarrow x \in X$   
and  $r(x_n, A) \rightarrow r(x, A) \checkmark$

To prove the boxed inequality, form a  
geodesic triangle with vertices  $x, y$   
and some  $a \in A$

then consider  
the comparison  
triangle in  $\mathbb{R}^2$





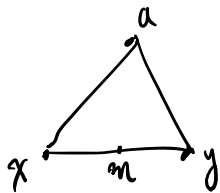
$$l_x = \sqrt{a^2 + b^2} \quad l_y = \sqrt{(a-r)^2 + b^2}$$

$$l_m = \sqrt{\left(a - \frac{r}{2}\right)^2 + b^2}$$

$$\begin{aligned} \text{So } \frac{1}{2}(l_x^2 + l_y^2) &= \frac{1}{2}(a^2 + b^2 + (a^2 - 2ar + r^2 + b^2)) \\ &= a^2 + b^2 - ar + \frac{r^2}{2} \end{aligned}$$

$$\begin{aligned} \text{and } l_m^2 &= a^2 - ar + \frac{r^2}{4} + b^2 \\ &= \frac{1}{2}(l_x^2 + l_y^2) - \frac{r^2}{4} = \frac{1}{2}(l_x^2 + l_y^2) - \frac{d(x,y)^2}{4} \end{aligned}$$

So back in  $X$  we have



$$d(m,a)^2 \leq \frac{1}{2}(d(x,a)^2 + d(y,a)^2) - \frac{d(x,y)^2}{4}$$

or

$$d(x,y)^2 \leq 2(d(x,a)^2 + d(y,a)^2 - 2d(m,a)^2)$$

For  $a$  with  $d(m,a)$  maximal, i.e.  $d(m,a) = r(m,A)$

$$\begin{aligned} \text{we get } d(x,y)^2 &\leq 2(d(x,a)^2 + d(y,a)^2 - 2r(m,A)^2) \\ &\leq 2(r(x,A)^2 + r(y,A)^2 - 2r(m,A)^2) \end{aligned}$$

Since  $r(m,A) \geq r(A)$  this becomes

$$d(x,y)^2 \leq 2(r(x,A)^2 + r(y,A)^2 - 2r(A)^2) \quad \checkmark$$



Now we can prove the theorem.

Theorem A  $\text{CAT}(0)$  group  $G$  has only finitely many conjugacy classes of finite subgroups.

Proof

Suppose  $H$  is a finite subgroup of a  $\text{CAT}(0)$  group  $G$ .

$G$  acts properly and cocompactly by isometries on a  $\text{CAT}(0)$  space  $X$ , so  $H$  fixes the circumcenter  $x$  of an orbit, i.e.  $H$  is contained in the (finite) stabilizer  $G_x$ .

Cover  $X$  by translates of a compact set  $K$  containing  $x$ .

The action is proper, so  $\Sigma = \{g \mid gK \cap K \neq \emptyset\}$  is finite. Since  $G_x \subset \Sigma$ , there are only finitely many possibilities for  $G_x$ , so for  $H$ .

If  $H$  fixes some  $y \notin K$  then  $y \in gK$  for some  $g$ , i.e.  $g^{-1}y = x \in K$  and  $G_y = gG_xg^{-1}$  is conjugate to (one of the finitely many)  $G_x$  for  $x \in K$ .

CAT(0) groups, like hyperbolic groups, are always finitely presented, but again the proof is very different.

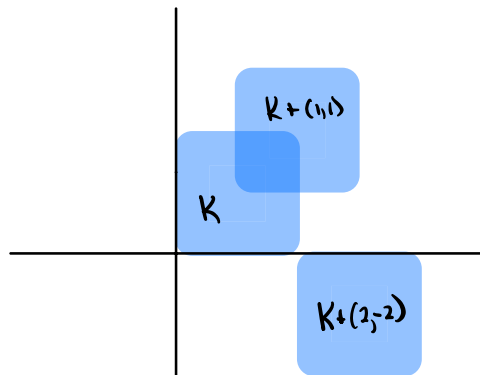
Hyperbolic groups are finitely-generated by definition, and we used short loops in (any) Cayley graph to get a set of relations.

For CAT(0) groups, it follows from the the Svarc-Milnor lemma that they are finitely generated.

Recall the proof:  $G \curvearrowright X$  CAT(0) proper, cocompact. Take  $K \subset X$  compact such that  $G \cdot U = X$  where  $U = \text{interior}(K)$ .

Then  $S = \{g \mid gU \cap U \neq \emptyset\}$  generates  $G$ , and  $S$  is finite because  $S \subset \{g \mid gK \cap K \neq \emptyset\}$ , which is finite because the action is proper.

A simple example to think about is the usual picture of  $G = \mathbb{Z}^2$  acting on  $\mathbb{R}^2$ . Take  $K = [0, 2] \times [0, 2]$ . Then translates of its interior  $(0, 2) \times (0, 2)$  cover  $\mathbb{R}^2$ .



$$S = \{ (\pm 1, 0), (0, \pm 1), (\pm 1, \pm 1) \}$$

We can eliminate inverses and just write

$$S = \{ (1, 0), (0, 1), (1, 1), (1, -1) \}$$

Note the elements of  $S$  are not independent:  $(1, 0) + (0, 1) = (1, 1)$

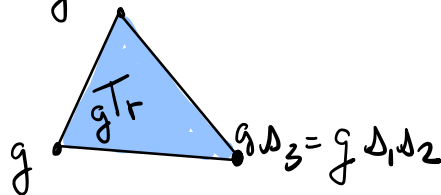
Theorem Let  $S$  be the generators given by

the S-M lemma, and

$$\text{let } R = \{ \Delta_1 \Delta_2 \Delta_3^{-1} \mid \Delta_i \in S, \Delta_1 \Delta_2 = \Delta_3 \text{ and } \cup \Delta_1 \cup \cup \Delta_3 \cup \neq \emptyset \}$$

Then  $G \cong \langle S \mid R \rangle$ , ie  $\ker F(S) \rightarrow G$  is normally generated by  $R$ .

Proof: Look at  $\mathcal{C}(G, S)$ . For each  $g \in G$  and each  $r = \Delta_1 \Delta_2 \Delta_3^{-1} \in R$ , give a triangle  $gT_r$  to the loop



to get a complex  $\mathcal{K} = \mathcal{C} \cup \{ gT_r \mid g \in G, r \in R \}$

$G$  acts freely and properly on  $K$ , so  $K \rightarrow K/G$  is a covering space

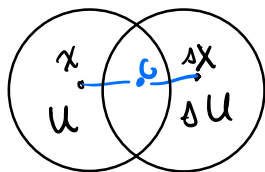
If we can prove  $K$  is simply-connected, then  $K$  is the universal cover, and

$$G = \pi_1(K/G) = F(S)/\langle\langle R \rangle\rangle \text{ by Van Kampen's theorem.}$$

We do know  $X$  is simply connected; we will use this to show  $K$  is. First define a map  $p: K \rightarrow X$  as follows: choose  $x \in X$

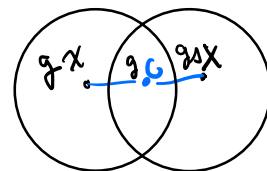
Vertices of  $K$  are group elements  $g$ . Define  $p(g) = gx$ .

There is an edge  $g \text{ --- } g^s$  in  $K$   
 $\Leftrightarrow U \cap sU \neq \emptyset$ . Choose  $c \in U \cap sU$ .  
 We may assume  $U$  is connected (otherwise replace  $K$  by a ball containing it)

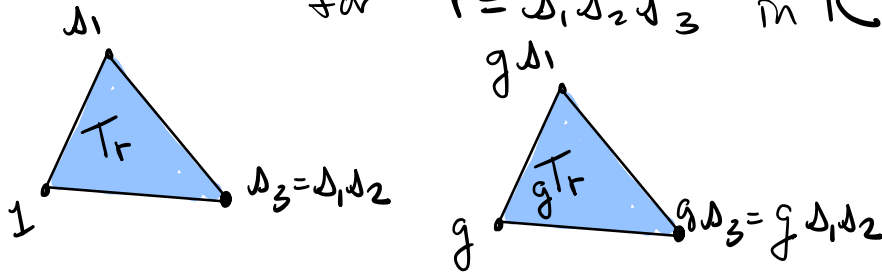


Connect  $x$  to  $c$  and  $c$  to  $sx$

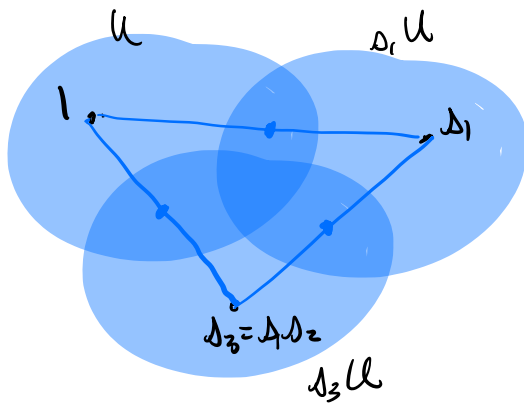
Then send  $g \text{ --- } g^s$  to the path  $gx - gc - gsx$ :



Now have  $p: \mathcal{C}(G, S) \rightarrow X$ .  
 Triangles in  $K$  are translates of  $T_r$ ,  
 for  $r = \delta_1 \delta_2 \delta_3^{-1}$  in  $R$



The image of  $\partial T_r$  in  $X$  is



where  $U \cap \delta_1 U \cap \delta_3 U \neq \emptyset$ .

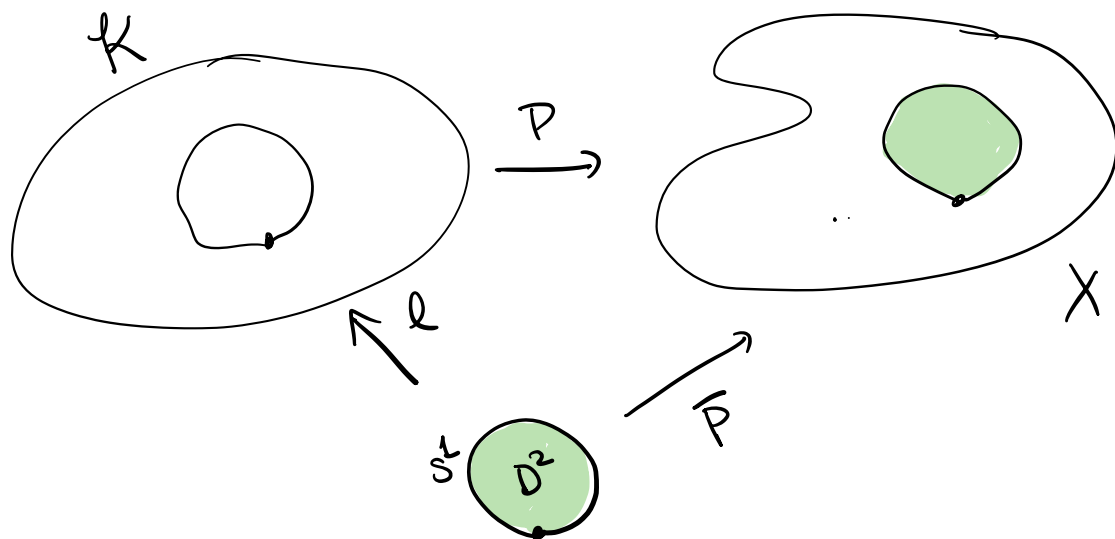
$X$  is 1-connected, so  $p|_{\partial T_r}$  extends to  $T_r$ ;

Extend equivariantly to all triangles  $gT_r$ .

To show  $K$  is 1-connected: Let

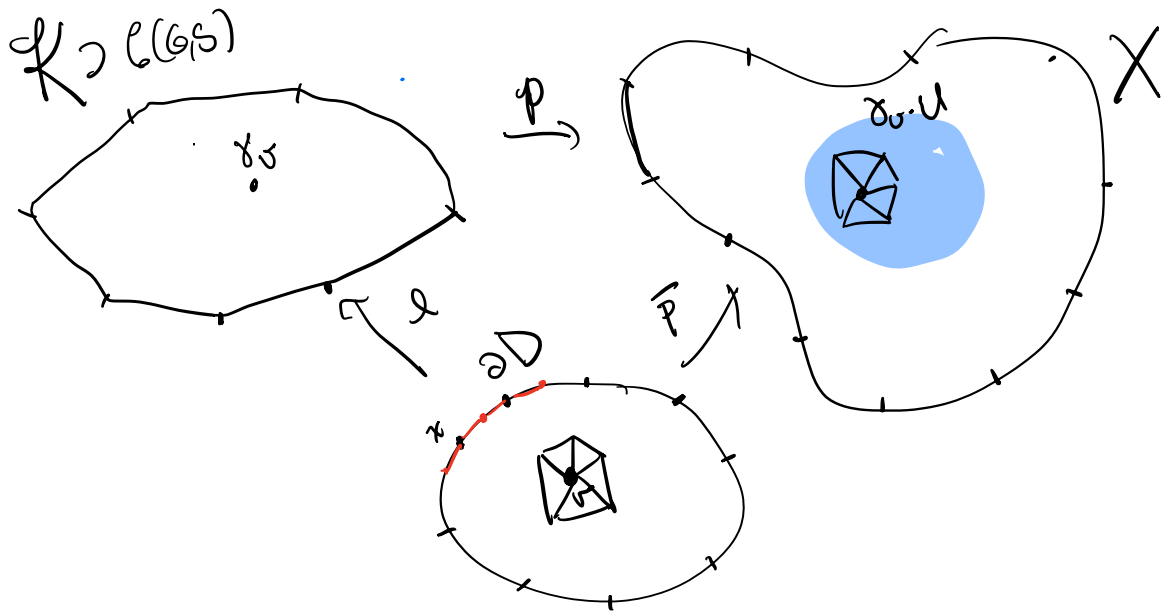
$l: S^1 \rightarrow K$  be a loop.

$p \circ l: S^1 \rightarrow X$  extends to  $\bar{p}: D^2 \rightarrow X$   
 since  $X$  is 1-connected.

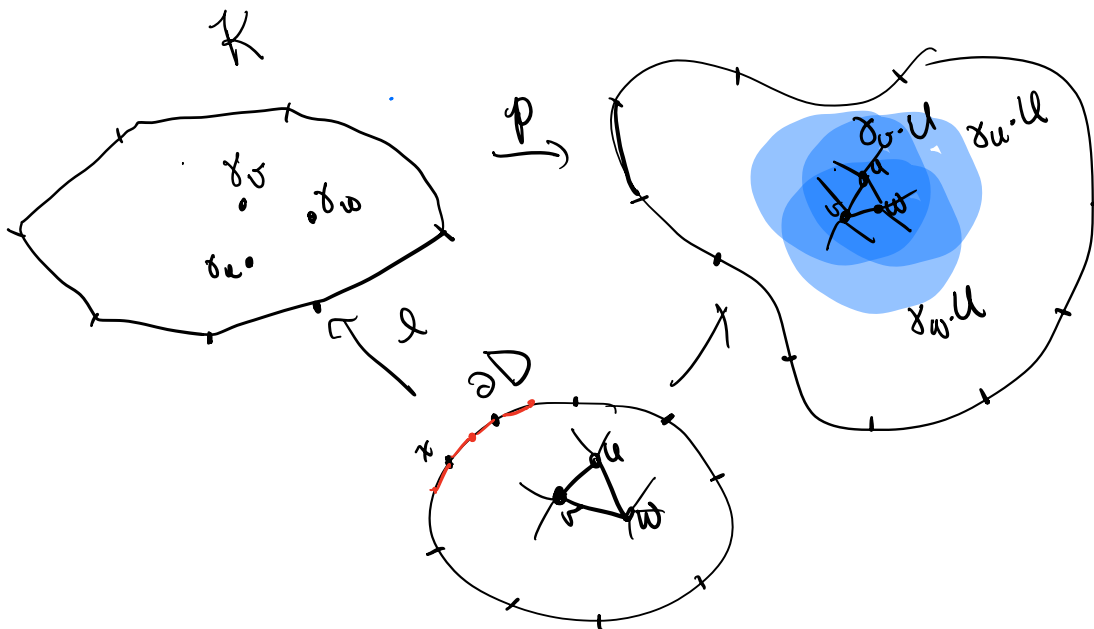


Triangulate  $D$  finely enough so that the all triangles around a vertex  $v$  map into a single translate  $\delta_v U$ . (The Lebesgue lemma guarantees that you can do this: let  $\lambda$  be the Lebesgue number of the cover  $\{\bar{p}^{-1}(yU)\}$  of  $D^2$ , and subdivide until the triangles around  $v$  have diameter less than  $\lambda$ .)

Locate  $\delta_v$  in  $\mathcal{C}(G, S) \subset K$



Let  $t = \Delta(u, v, w)$  be a triangle in  $D$



Then  $\Delta(u, v, w) \subset \delta_u \cdot U \cap \delta_v \cdot U \cap \delta_w \cdot U$   
 In particular, this intersection is not  $\emptyset$ .

$$\begin{aligned} & \gamma_v U \cap \gamma_u U \cap \gamma_w U \\ &= \gamma_v (U \cap \gamma_v^{-1} \gamma_u U \cap \gamma_v^{-1} \gamma_w U) \neq \emptyset \end{aligned}$$

so  $d_1 = \gamma_v^{-1} \gamma_u \in S$   
 $d_3 = \gamma_v^{-1} \gamma_w \in S$   
 and  $d_2 = \gamma_u^{-1} \gamma_w \in S \quad (\gamma_u^{-1} \gamma_v U \cap U \cap \gamma_u^{-1} \gamma_w U) \neq \emptyset$

Since  $d_1 d_2 = d_3$ ,  $d_1, d_2, d_3^{-1} \in R$   
 so there's a triangle in  $K$  with vertices  $\gamma_u, \gamma_v, \gamma_w$

Now map  $\Delta(a, v, w) \rightarrow \Delta(\gamma_u, \gamma_v, \gamma_w) \subset K$ .

Doing this for all triangles in  $D$   
 extends  $l: \partial D \rightarrow K$   
 to  $f: D \rightarrow K$

$\therefore K$  is 1-connected and we're done

Below I list some other known properties of CAT(0) groups, and compare them to properties of hyperbolic groups!



We showed an infinite hyperbolic group has an infinite-order element.

- ★ This is also true for  $CAT(0)$  groups. For hyperbolic groups we used the fact that they have only finitely many cone types, but that may not be true for  $CAT(0)$  groups (at least our proof doesn't work...)

If  $G$  is hyperbolic, we found a presentation with a linear Dehn function — and stated the fact that the Dehn function of any presentation is linear, and this characterizes hyperbolic groups.

- ★ The Dehn function of a  $CAT(0)$  group is at most quadratic — but not all groups with quadratic Dehn functions are  $CAT(0)$ .

- ★  $CAT(0)$  groups have solvable word and conjugacy problems

Hyperbolic groups satisfy a Tits alternative  
every subgroup is either virtually  
cyclic or contains a copy of  $F_2$

- \* Solvable subgroups of  $CAT(0)$  groups  
are virtually abelian
- \* Abelian subgroups of  $CAT(0)$  groups  
are finitely-generated

So a natural analog for  $CAT(0)$   
groups would be

A subgroup of a  $CAT(0)$  group is  
either virtually abelian or  
contains a copy of  $F_2$ .

This is an open problem, though it is  
known to be true for some classes  
of  $CAT(0)$  groups.

## Gromov's link condition

We've noted that  $CAT(0)$  groups have nice properties, but it is not so clear how to decide whether a group is  $CAT(0)$ .

The best source of examples is the Cartan-Hadamard theorem, saying that if  $Y$  is NPC (locally  $CAT(0)$ ) then its universal cover is  $CAT(0)$ ; since  $\pi_1 Y$  acts properly (in fact freely) on  $\tilde{Y}$ , we get  $\pi_1 Y$  is  $CAT(0)$  for compact NPC spaces  $Y$ .

But it's not so easy to decide whether a space is locally  $CAT(0)$ .

If  $Y$  is a locally finite polyhedral complex, Gromov gave a necessary and sufficient condition.

Def A polyhedral complex is a union of convex Euclidean polyhedra, glued together along faces by isometries.

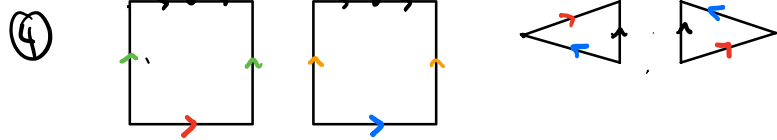
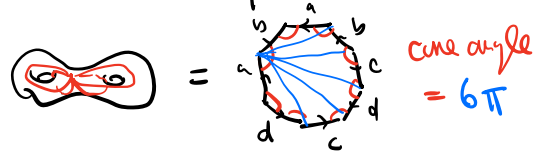
The metric is given by  
 $d(x, y) = \inf(\text{length of shortest piecewise linear path from } x \text{ to } y)$

## Examples

① A graph with positive edge lengths

② A flat torus 

③ A surface with a cone point



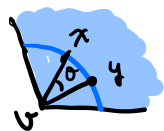
## Gromov's link condition

Let  $Y$  be a polyhedral complex and  $v$  a vertex. Let  $\delta$  be the length of the shortest 1-cell in  $Y$  and  $\varepsilon \ll \delta$ . The link of  $v$  is

$$\text{Lk}(v) = \{x \in X \mid d(x, v) = \varepsilon\}$$

The intersection of  $\text{Lk}(v)$  with each  $n$ -cell

is an  $(n-1)$ -cell contained in a Euclidean sphere of radius  $\varepsilon$ . Measure the distance between two points in this cell by the angle they form with  $v$

$$d(x, y) = \angle xvy \quad \text{d}(x, y) = \theta$$


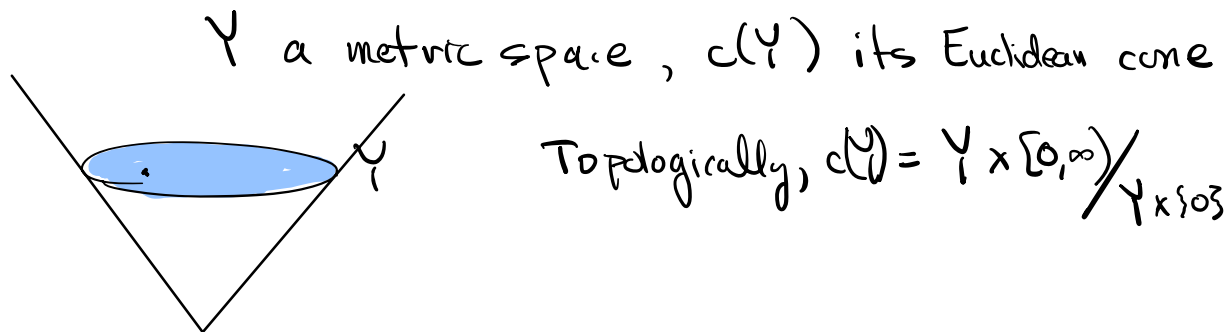
Theorem (Gromov) A polyhedral complex  $Y$  is NPC if and only if the link of every vertex is CAT(1)

CAT(1) : Every triangle with perimeter  $< 2\pi$  is thinner than a triangle with the same edge lengths on the unit sphere  $S^2 \subset \mathbb{R}^3$ .

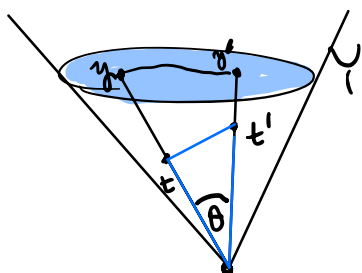
Comments on proof:

Points in the interior of top-dimensional cells have Euclidean ( $\therefore$  CAT(0)) neighborhoods.

A neighborhood of a vertex  $\sigma$  is a cone on  $Lk(\sigma)$



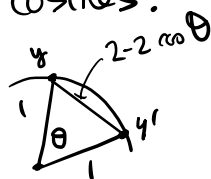
The metric on  $c(Y)$  is given as follows:



Let  $d_Y(y, y') = \min(\pi, d(y, y'))$ . Then

$$d((y, t), (y', t'))^2 = t^2 + t'^2 - 2tt'(\cos d_Y(y, y'))$$

If  $Y \subset$  unit sphere in  $\mathbb{R}^n$ ,  
 $d(y, y') = \text{angle } \angle y o y'$ , so this is the law of cosines:  
 $t = t' = 1 \Rightarrow d = \begin{cases} 2 & \text{if } d(y, y') \geq \pi \\ 2 - 2 \cos d(y, y') & \text{if } d(y, y') < \pi \end{cases}$



Berestovskii's Theorem:  $d(Y)$  is  $CAT(0)$

if and only if  $Y$  is  $CAT(1)$ .

PF Bridson-Haefliger Thm II.3.14 (p.188)

So this shows that vertices have  $CAT(0)$  neighborhoods.

A neighborhood of a point on an edge adjacent to  $u$  is  $(-\varepsilon, \varepsilon) \times c(Lk_L(u))$  where  $L = Lk_Y(u)$ .

Berestovskii's theorem also works for  $CAT(k)$  spaces, in particular, one can define a spherical cone  $C_1(Y)$  and prove  $C_1(Y)$  is  $CAT(1)$  if and only if  $Y$  is  $CAT(1)$ .

So this will give a  $CAT(0)$  neighborhood of points on edges.

Points on faces of larger dimension are also of the form  $B_\varepsilon \times c(Lk_L(u))$ , where  $B_\varepsilon$  is a Euclidean ball and  $L$  is a link in a previous link, and the theorem is proved by induction. //

Even with Gromov's theorem, it's hard to tell whether a polyhedral complex is  $CAT(0)$  - unless it's 2-dimensional

If  $Y$  is 2-dimensional, the link of every vertex is (at most) 1-dimensional, i.e. it's a graph plus some isolated points



When is a graph  $CAT(1)$ ? We just have to check triangles with perimeter  $< 2\pi$

in  $S^2$ , such a triangle lives in a hemisphere



If you have a triangle in a graph, the only way to get to another side is to travel through the edges. But on the sphere there's a shorter path:



I.e. a graph is  $cat(1)$  iff it has no loops of length  $< 2\pi$ .

Example ④ above of a polyhedral complex satisfies this criterion (exercise!), so the fundamental group  $G$  is CAT(0).  
 By van Kampen's theorem  $G$  has the presentation

$$G = \langle a, b, s, t \mid [a, b] = 1, s^{-1}(ab)^2s = b, t^{-1}(ab)^2t = a \rangle$$

The map  $G \rightarrow G$  sending  $a \rightarrow a^2, b \rightarrow b^2, s \rightarrow s$  and  $t \rightarrow t$  sends the relations to id, so induces a homomorphism  $f: G \rightarrow G$

It's easy to see  $f$  is surjective.

Dani Wise showed  $f$  is not injective.

For finitely generated linear groups (ie subgroups of  $GL(n, \mathbb{C})$ ), any surjective homomorphism is an isomorphism, so this proves that  $G$  is not linear

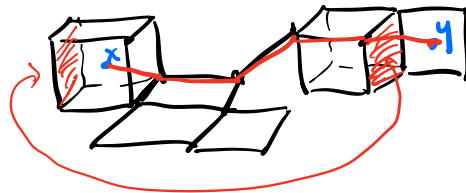
This was the first example of a CAT(0) group which is not linear, answering a question of Gromov.



If  $Y$  is more than two-dimensional,  
 Gromov's link condition becomes  
 difficult to check —  
unless all the cells are cubes  $[0,1]^n$ .

Cube complexes - Polygonal complexes, all  
 polygons are cubes  $[0,1]^n$

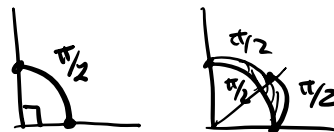
Picture: metric cubes  $[0,1]^n$  glued together by  
 isometries of their faces.



$d(x,y)$  = length of shortest path from  $x$  to  $y$ .

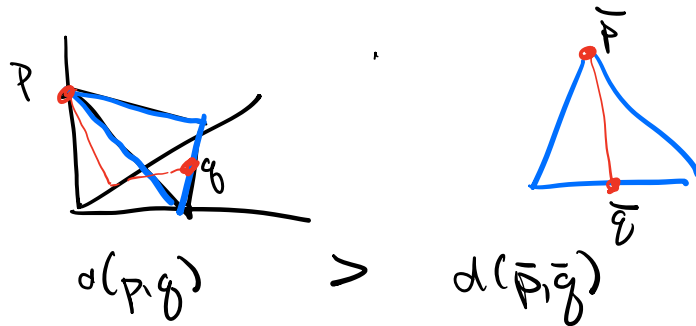
It turns out there is a purely combinatorial  
 way to check the link condition for cube  
 complexes:

In a cube, the link of a vertex is an  
 "all-right" spherical simplex:



So  $Lk(v)$  is a simplicial complex, and  
 all edges have length  $\pi/2$ .

Note that the boundary of a 3-dim cube is not locally CAT(0) : at a corner we have a triangle that is fatter than a Euclidean comparison triangle:



But if you fill in the cube, this problem disappears.

Def A simplicial complex  $\Sigma$  is a flag complex if whenever  $\Sigma$  contains the 1-skeleton of a simplex, it also contains the simplex



**Theorem** (Gromov) A cube complex is NPC if and only if the link of every vertex is a flag complex

Proof By Gromov's theorem,

It suffices to prove that a simplicial complex made of all-right spherical simplices is CAT(1) if and only if it is flag. This is proved by induction on  $\dim(Y)$ .

If  $\dim(Y) = 2$ , this says that a link graph cannot contain a triangle with all side lengths  $\pi/2$ , so is a direct consequence of Gromov's link condition, as we discussed above

If  $\dim Y > 2$ , this requires some spherical geometry plus induction.

For the full proof, see Bridson-Haefliger, theorem 5.18. //

## Cube complexes and RAAGs

We have:

**Theorem (Gromov)** A locally finite cube complex  $Y$  is NPC if and only if the link of every vertex is a flag complex


We can use this to prove certain groups are CAT(0):

**Definition** A **right-angled Artin group (RAAG)** is a finitely-generated group with a presentation  $\langle S | R \rangle$ , where all  $r \in R$  are of the form  $s_1 s_2 s_1^{-1} s_2^{-1}$  (ie  $s_1 s_2 = s_2 s_1$ ) for  $s_1, s_2 \in S$ .

The presentation is conveniently encoded by drawing a (simplicial) graph  $\Gamma$

vertices = elements of  $S$   
edge  $s_1 - s_2 \iff s_1 s_2 s_1^{-1} s_2^{-1} \in R$

The RAAG is then called  $A_\Gamma$

eg  $\Gamma =$    $A_\Gamma = \langle a, b, c \mid ab=ba \rangle$   
 $= \mathbb{Z}^2 * \mathbb{Z}$   
 $\langle a, b \rangle \quad \langle c \rangle$

RAAGs include free groups:

$$\Gamma = \overset{a}{\cdot} \cdot \overset{b}{\cdot} \cdot \overset{c}{\cdot} \quad (\text{no edges})$$

and free abelian groups:

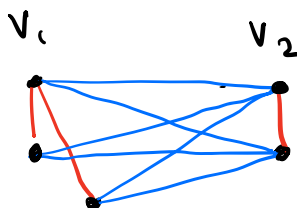
$$\Gamma = \begin{array}{ccc} & a & b \\ & \diagdown & \diagup \\ c & & d \\ & \diagup & \diagdown \end{array} \quad (\text{complete graph})$$

Free products of RAAGs are RAAGs:

$$\text{If } \Gamma = \Gamma_1 \sqcup \Gamma_2, \text{ then } A_\Gamma = A_{\Gamma_1} * A_{\Gamma_2}$$

Direct products of RAAGs are RAAGs:

$\Gamma$  is a join if  $V(\Gamma) = V_1 \sqcup V_2$ , and every vertex of  $V_1$  is connected to every vertex of  $V_2$ :



$$\text{Then } A_\Gamma = A_{\Gamma_1} \times A_{\Gamma_2}$$

But in general there is no simple way to decompose  $A_\Gamma$

Interesting examples of RAAGs include

$$\Gamma = \text{---} \cdot \text{---} \cdot \text{---} \cdot \begin{array}{l} \nearrow \\ \text{---} \\ \searrow \end{array} = \pi_1(\mathbb{3}\text{-manifold}) \quad (\text{True whenever } \Gamma \text{ is a tree})$$

RAAGs contain surprising subgroups

$$\Gamma = \text{---} \cdot \text{---} \cdot \text{---} \cdot \text{---} \cdot \text{---} \cong \pi_1(\Sigma_g) \text{ (surface group)}$$

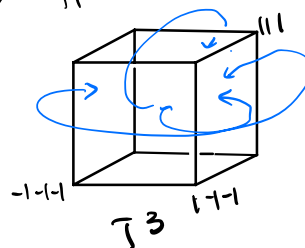
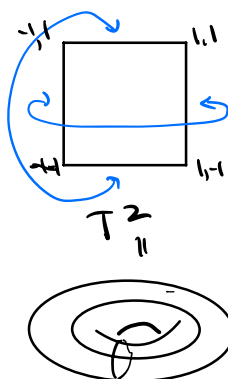
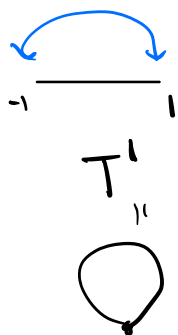
Claim  $A_\Gamma$  is always CAT(0)

Proof: We exhibit  $A_\Gamma$  as  $\pi_1$  of an NPC cube complex  $S_\Gamma$ .

First, recall that a k-clique on  $\Gamma$  is a set of  $k$  vertices  $v_1, \dots, v_k$  that form a complete subgraph.

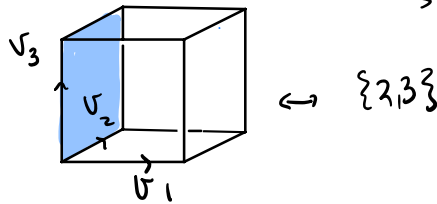
We give two descriptions of  $S_\Gamma$

① Let  $T^n$  be the  $n$ -Torus  $[-1, 1]^n / \text{opposite sides}$ :

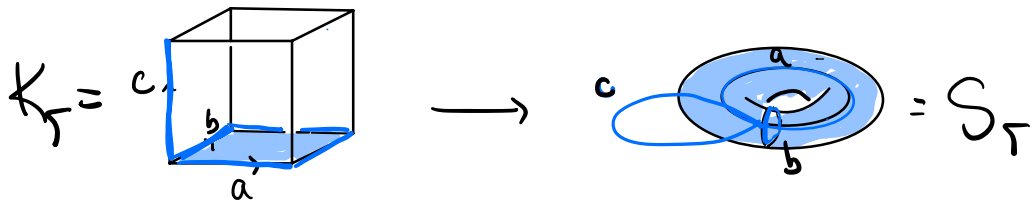


(can't draw)

$k$ -dimensional faces of  $[-1,1]^n$  at  $(-1, \dots, -1)$   
 $\leftrightarrow$  subsets of  $\{1, \dots, n\}$



If  $\Gamma$  has  $n$  vertices, let  $K_\Gamma \subset [-1,1]^n$  be the subcomplex consisting of faces corresponding to cliques in  $\Gamma$ , and  $S_\Gamma$  the image of  $K_\Gamma$  in  $T^n$ :



## ② Second description of $S_\Gamma$

$S_\Gamma$  is the cube complex formed as follows.

- start with one 0-cube (vertex)  $p$
- attach an edge for each vertex of  $\Gamma$  (= generator of  $A_\Gamma$ )  
 - it becomes a loop
- Attach a square for each edge of  $\Gamma$  -  
 it becomes a torus

So far we have the presentation complex for  $A_\Gamma$ , ie a 2-dimensional complex with  $\pi_1 = A_\Gamma$  (by Van Kampen)

But we're not done

- Attach a  $k$ -cube for each  $k$ -clique in  $\Gamma$  - it becomes a  $k$ -torus

Now we're done.

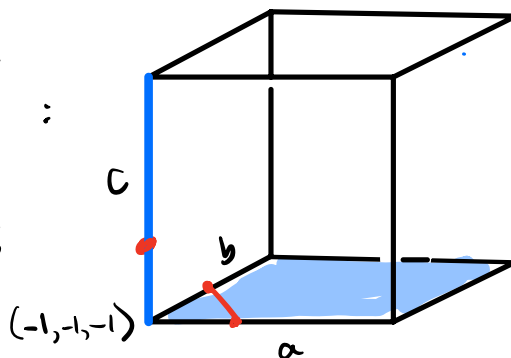
Attaching higher-dimensional cubes does not change  $\pi_1$  (Any loop in  $X$  can be pushed into the 2-skeleton), so  $\pi_1(S_\Gamma) = A_\Gamma$ .

Claim:  $S_\Gamma$  is an NPC complex.

We use Gromov's link condition for cube complexes. There's only one link to check since there's only one vertex

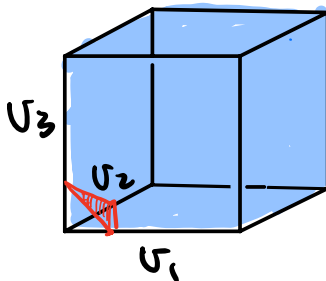
In  $[1,1]^n$  we have a subcomplex  $K_\Gamma$ :

llc  $K_\Gamma(-1,-1,-1) = \Gamma!$





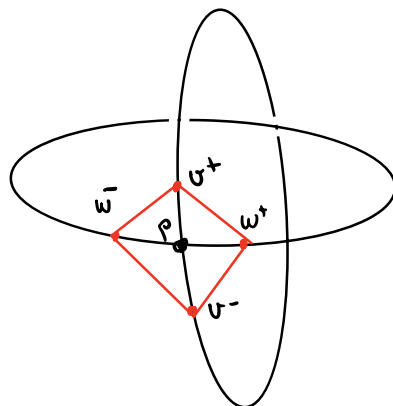
If  $v_1, \dots, v_k$  are a clique then every pair  $v_i, v_j$  is joined by an edge, so we have the boundary of a  $(k-1)$ -simplex. But we've filled in the cube, so this  $(k-1)$ -simplex bounds a simplex in  $\text{lk}(-1, \dots, -1)$



Definition The flag completion  $\tilde{\Gamma}$  is the flag complex with 1-skeleton  $\Gamma$ .  
So  $\text{lk}_{K_{\Gamma}}(-1, \dots, -1) = \tilde{\Gamma}$ .

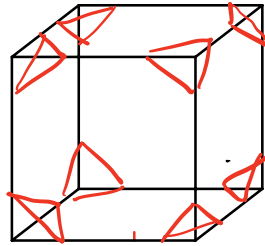
But this is the link in  $K_{\Gamma}$ , not in  $S_{\Gamma}$ .  
In  $T^n$  each edge becomes a loop at  $p$ .  
each vertex in  $\Gamma$  corresponds to 2 vertices  $v^+, v^-$  in  $\text{lk}_{S_{\Gamma}}(p)$ :

$v^{\pm}, w^{\pm}$  are joined by an edge  $\Leftrightarrow v, w$  are joined by an edge in  $\Gamma$  :



Definition The double  $D(\Gamma)$  of a simplicial graph  $\Gamma$  is the graph with two vertices  $v^+, v^-$  for every vertex of  $\Gamma$  and an edge  $v^\pm$  to  $w^\pm$  for every edge  $v$  to  $w$  in  $\Gamma$ .

Vertices  $v_1^\pm, \dots, v_k^\pm$  form a clique in  $D(\Gamma)$  and only if  $v_1, \dots, v_k$  forms a clique in  $\Gamma$ , so that  $v_1, \dots, v_k$  are the vertices of a  $(k-1)$ -cube  $C \in K_\Gamma$



All  $2^k$  cliques are filled in, by the images of the links of the  $2^k$  vertices of  $C$  in  $S_\Gamma$ .

ie The link  $ll_{S_\Gamma}(p)$  is the flag completion  $\widehat{D(\Gamma)}$  of  $D(\Gamma)$ .

Since this is flag,  $S_\Gamma$  is NPC and  $\pi_1 S_\Gamma = A_\Gamma$  is CAT(0).

Note that  $\Gamma$  is an arbitrary simplicial graph  
 so  $S_\Gamma$  can be pretty wild...

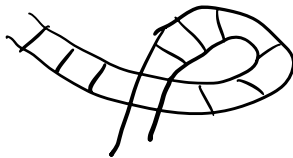
but not too wild:

They don't contain:

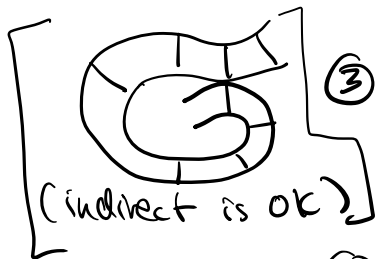
① Mobius bands



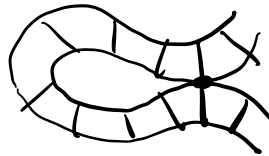
②



self-intersecting  
cube chains

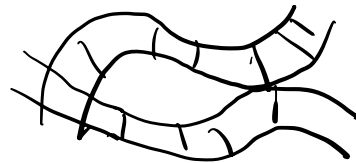


③



direct  
self-osculating  
chains

④

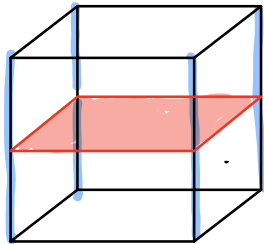


inter-osculating  
chains

Def a cube complex satisfying ①-④ is  
 a special cube complex

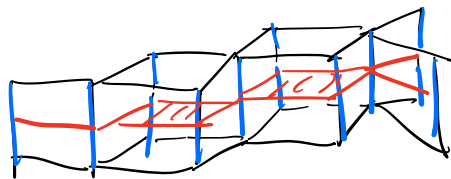
Not all special cube complexes are Salvetti  
 complexes  $S_\Gamma$ , but Haglund and Wise  
 showed they are closely related, by  
 studying hyperplanes in special cube complexes.

Def The midplane of a cube  $C = [-1, 1]^n$  is the intersection of a coordinate hyperplane with  $C$



The midplanes give an  $\sim$  relation on the edges of a cube

The equivalence relation on edges of  $X$  generated by a single edge gives a hyperplane in  $X$



Given a special cube complex  $Y$ , define a graph (called the crossing graph of  $Y$ )

vertices = hyperplanes  $H$

edge  $H - H'$  if  $H$  and  $H'$  intersect transversely.

Thm (Haglund-Wise) If  $X$  is a special NPC cubecomplex, then  $\pi_1 X \hookrightarrow A_\Gamma$ , where  $\Gamma$  is the crossing graph of  $X$ .

One nice feature of RAAGs is the following:

Theorem (Davis-Januskiewicz): RAAGs are linear

(Recall we had an example of a CAT(0) group that is not linear a couple of lectures ago)

The proof proceeds by proving every RAAG embeds as a finite index subgroup of a right-angled Coxeter group  $C_\Gamma$

Def: Let  $\Gamma$  be a <sup>finite</sup> simplicial graph. The right-angled Coxeter group  $C_\Gamma$  is the group given by the presentation  $\langle S | R \rangle$  where

- $S = \text{vertices of } \Gamma$
- $\Delta^2 \in R$  for all  $s \in S$
- All other elements of  $R$  are of the form  $s_1 s_2 s_1^{-1} s_2^{-1}$

Right-angled Coxeter groups can be realized as linear reflection groups: the generators correspond to reflections in hyperplanes, they commute if the hyperplanes intersect at right angles

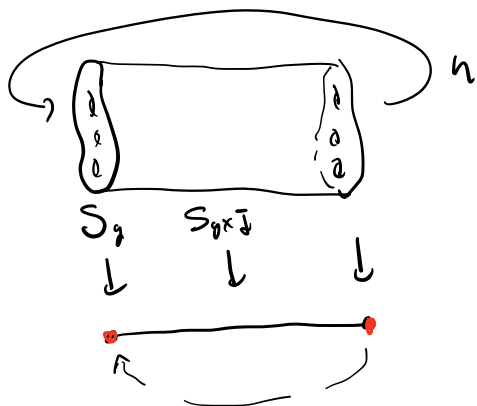
Major earthquake in 3-manifold theory:

Thm (Agol, 2012):  $M^3$  a compact orientable irreducible hyperbolic 3-manifold has a finite cover whose fundamental group acts properly and cocompactly on a special CAT(0) cube complex i.e.  $\pi_1 M^3$  has a finite index subgroup that embeds in a RAAG.

In particular, this subgroup is linear (→ topol, resid. finite, Tits, ...)

This was the last piece of a puzzle about the structure of 3-manifolds:

Every closed hyperbolic 3-manifold has a finite cover that is a surface bundle over a circle:



glue ends together by a homeomorphism  $h$   
 $M^3 = S_g \times [0,1] / (x,0) \sim (h(x),1)$

(True for all closed, orientable, irreducible 3-manifolds, using Perelman + more work (2018))

Finally, a very quick word about automorphism groups  $\text{Aut}(G)$  and

$$\text{Out}(G) = \frac{\text{Aut}(G)}{\text{Inn}(G)} \text{ for } G \text{ hyperbolic or CAT}(0)$$

$$\text{eg } \text{Aut}(\mathbb{Z}^n) = \text{GL}_n \mathbb{Z} = \text{Out}(\mathbb{Z}^n)$$

$$\text{Out}(F_n) = \text{Aut}(F_n) / \text{Inn}(F_n)$$

$$\text{Out}(A_\Gamma) = \text{Aut} / \text{Inn}$$

$$\text{Out}(\pi_1 S_n) = \text{Aut} / \text{Inn}$$

$$= \Gamma_g \text{ mapping class group}$$

These groups are almost never hyperbolic or CAT(0) ( $\text{SL}_2 \mathbb{Z}$  is an exception)

$\text{SL}_2 \mathbb{Z}$  acts on  $\mathbb{H}$  properly but not cocompactly, so is not QI to  $\mathbb{H}$

But you can still use this action and the geometry of  $\mathbb{H}$  to study the group.

There are analogous spaces  $\mathcal{O}_G$

$$G = \text{SL}_n \mathbb{Z}, \text{Out}(F_n), \text{Out}(\pi_1 S_g), \text{Out}(A_\Gamma)$$

with proper actions that are not cocompact

(though this can be fixed)

Points on  $\mathcal{O}_G$  are (CAT(0), hyperbolic) spaces  $X$  together with an isomorphism

$$\mu: \pi_1(X) \cong G, \text{ called a marking}$$

An automorphism of  $G$  acts by changing the marking

$$\begin{array}{ccc} G & \xrightarrow{\mu} & \pi_1 X \\ \uparrow \alpha & \nearrow \mu \alpha & \\ G & & \end{array}, \text{ not the metric on } X$$

You move around the space by deforming the metric on  $X$  (think about deforming the parallelogram that defines a flat torus)

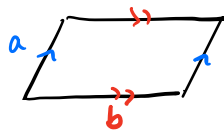
You can study the topology and geometry of  $\mathcal{O}_G$  to learn about  $\text{Out}(G)$ .

This is classical for  $G = \mathbb{Z}^n$  (Symmetric spaces)  
slightly newer for  $G = \pi_1 S_g$  (Teichmüller space)  
slightly newer for  $G = F_n$  (Outer space)  
very recent for  $G = A_\Gamma$ .



For  $G = \mathbb{Z}^n$ , use  $X = \text{flat torus}$ .

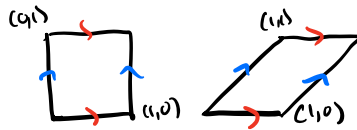
eg  $n=2$



Different shaped parallelograms give different points in  $\mathcal{O}_G$

Some parallelograms give the same (ie isometric) flat torus:

eg

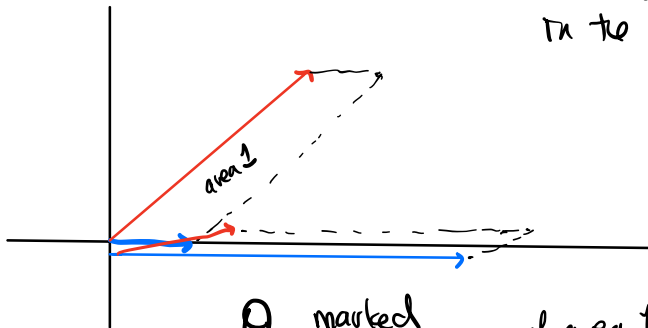


but with a different marking, ie choice of isomorphism

$$\mathbb{Z}^2 \longrightarrow \pi_1(T)$$

If we normalize so that  $\text{area}(T^2) = 1$  and put one edge on the  $x$ -axis, the other edge gives a unique point

in the upper half-plane



So the space of  $\mathbb{Z}^2$  marked flat tori of area 1 can be identified with  $\mathbb{H}^2$ .

$$\mathbb{H}^2 = \text{SL}(2, \mathbb{R}) / \text{SO}(2) = \text{symmetric space for } \text{GL}_2$$

The action of  $\text{SL}(2, \mathbb{Z})$  on  $\mathcal{O}_{\mathbb{Z}^2}$  is the action by Möbius transformations that we already studied.

For  $n > 2$ , also get the space of marked flat tori of volume 1 =

$$SL(n, \mathbb{R}) / SO(n) \quad (= GL(n, \mathbb{R}) / O(n))$$

and  $SL_n(\mathbb{Z})$  acts on the left by changing the marking but not the isometry type of the torus.

For  $G = \pi_1 \Sigma_g$  we use hyperbolic surfaces of area 1 homeomorphic to  $\Sigma_g$

$\mathcal{O}_{\pi_1 \Sigma_g}$  is called **Teichmüller space**

For  $G = F_n$  we use metric graphs with total edge length 1

$\mathcal{O}_{F_n}$  is called "Outer space"

For  $G = A_\Gamma$  we use special cube complexes with

$\pi_1 \cong A_\Gamma$  (Salvetti, twisted Salvetti,  
(twisted) blowups of Salvetti)  
to get an Outer space